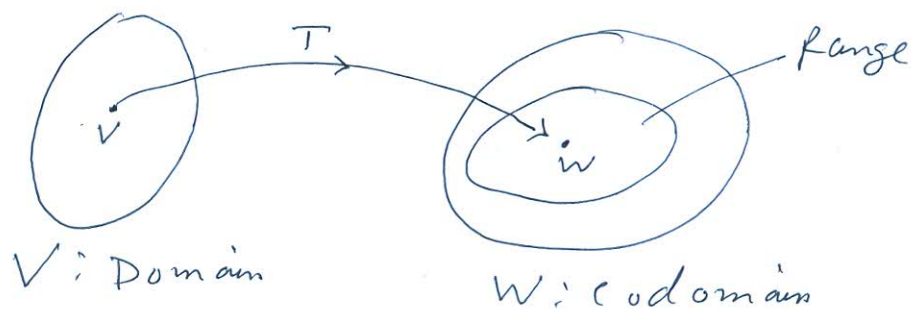


Week-11, chapter 3

Linear Transformations



$$T: V \rightarrow W$$

Function  $T$  that maps a vector space  $V$  into a vector space  $W$ :

Q1.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$   $v = (v_1, v_2) \in \mathbb{R}^2$ ,  $T(v_1, v_2) = (v_1 - v_2, v_1 + 2v_2)$   
 (a) Find the image of  $v = (-1, 2)$  (b) Find the pre-image of  $w = (-1, 11)$  ①

Sol: (a)  $v = (-1, 2)$

$$T(v) = T(-1, 2) = (-1 - 2, -1 + 2(2)) \text{ from } \textcircled{1}$$

$$= (-3, 3)$$

(b)  $T(v) = w = (-1, 11)$   $v \xrightarrow{T} w$

we know  $T(v_1, v_2) = (v_1 - v_2, v_1 + 2v_2) = (-1, 11)$

$$\text{So } \begin{cases} v_1 - v_2 = -1 \\ v_1 + 2v_2 = 11 \end{cases}$$

$$\text{So } \begin{cases} v_1 - v_2 = -1 \\ v_1 + 2v_2 = 11 \end{cases}$$

$$v_1 = 3, v_2 = 4$$

pre-image of  $(-1, 11)$

Linear Transformation: Let  $V, W$  be the vector space

$V \rightarrow W$ :  $V$  to  $W$  linear Transformation if

$$T(u+v) = T(u) + T(v) \quad \forall u, v \in V$$

Linear T  
T

Q1. Verify a linear Transformation  $T$  from  $\mathbb{R}^2$  into  $\mathbb{R}^2$

$$T(u_1, u_2) = (u_1 - u_2, u_1 + 2u_2) \quad \text{--- (1)}$$

Soln: let  $u = (u_1, u_2)$   $v = (v_1, v_2)$  and  $c$  is any real No.

1 - let  $u + v = (u_1, u_2) + (v_1, v_2) = (u_1 + v_1, u_2 + v_2)$

So

~~$T(u+v)$~~

$$T(u+v) = T(u_1 + v_1, u_2 + v_2)$$

$$= ((u_1 + v_1) - (u_2 + v_2), (u_1 + v_1) + 2(u_2 + v_2))$$

from (1)

$$= ((u_1 - u_2) + (v_1 - v_2), (u_1 + 2u_2) + (v_1 + 2v_2))$$

$$= (u_1 - u_2, u_1 + 2u_2) + (v_1 - v_2, v_1 + 2v_2)$$

$$= T(u) + T(v) \quad \text{from (1)}$$

2 - Scalar Multiplication

$$cu = c(u_1, u_2) = (cu_1, cu_2)$$

Now

$$T(cu) = T(cu_1, cu_2)$$

$$= (cu_1 - cu_2, cu_1 + 2cu_2) \quad \text{from (1)}$$

$$= c(u_1 - u_2, u_1 + 2u_2)$$

$$= cT(u)$$

Therefore,  $T$  is a linear Transformation.

Zero Transformation

$$T: V \rightarrow W \quad T(u) = 0 \quad \forall u \in W$$

Identity Transformation

$$T: V \rightarrow V \quad T(u) = u \quad \forall u \in V$$

Q1. Let  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be a L.T such that

$$T(1,0,0) = (2, -1, 4), \quad T(0,1,0) = (1, 5, -2) \\ T(0,0,1) = (0, 3, 1) \quad \text{Find } T(2, 3, -2)$$

Soln: we can write

$$(2, 3, -2) = 2(1, 0, 0) + 3(0, 1, 0) - 2(0, 0, 1)$$

*e.g. These are standard basis*  
Now Apply the Transformation both sides

$$T(2, 3, -2) = 2T(1, 0, 0) + 3T(0, 1, 0) - 2T(0, 0, 1) \\ = 2(2, -1, 4) + 3(1, 5, -2) - 2(0, 3, 1) \\ = (7, 7, 0)$$

Q2. The function  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  is defined by  $T(u) = Au =$

$$\begin{bmatrix} 3 & 0 \\ 2 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

(a) Find  $T(u)$  where  $u = (2, -1)$

Soln:

$$u = (2, -1)$$
$$T(u) = Au = \begin{bmatrix} 3 & 0 \\ 2 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \\ 0 \end{bmatrix}$$

$\mathbb{R}^2$  vector  $\downarrow$   $\mathbb{R}^3$  vector

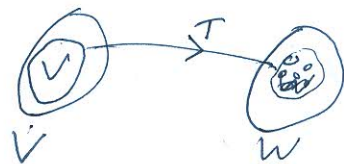
$$\therefore T(2, -1) = (6, 3, 0)$$



Kernel of a L-T: Let  $T: V \rightarrow W$  be a L-T. Then the set of all vectors  $v$  in  $V$  that satisfy  $T(v) = 0$  is called the kernel of  $T$  and it is denoted by ~~ker~~  $\ker(T)$

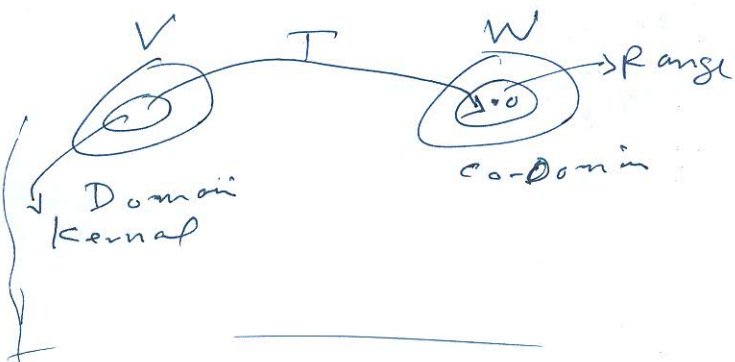
$$\ker(T) = \{v \mid T(v) = 0 \quad \forall v \in V\}$$

Note: Sometimes  $\ker T$  is called the Nullspace of  $T$



Range of a L-T: Let  $T: V \rightarrow W$  be a L-T

Then the set of all vectors ~~in~~  $w$  in  $W$  that are images of vectors in  $V$  is called the range of  $T$  and denoted by  $\text{range}(T)$



Note: (1)  $\ker(T)$  is a subspace of  $V$

(2)  $\text{range}(T)$  is a subspace of  $W$

Rank of a L-T: Let  $T: V \rightarrow W$

$\text{rank}(T) =$  The dimension of the range of  $T$

Nullity of L-T: Let  $T: V \rightarrow W$

$\text{nullity}(T) =$  The dimension of the kernel of  $T$

Dimensional Theorem for a L-T: Let  $T: V \rightarrow W$  be a L-T

$$\text{rank}(T) + \text{nullity}(T) = n$$

OR

$$\dim(\text{range of } T) + \dim(\ker \text{ of } T) = \dim(\text{domain of } T)$$

Q. Find the rank and Nullity of L-T

(3)

$$A = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Soln: we know rank  $(T) = \text{rank}(A) = 2$  no. of Non-Zero Rows

and nullity  $(T) = \dim(\ker T)$   
 $= \dim(\text{domain of } T)$   
 $= 3$

and given  $n = 3 \therefore$  matrix is  $3 \times 3$

So by rank nullity theorem

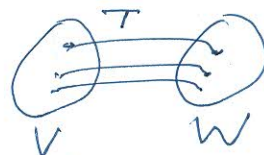
$$\text{rank}(T) + \text{nullity of } T = n$$

or nullity of  $(T) = n - \text{rank}(T)$

$$= 3 - 2$$

$$\text{nullity}(T) = 1$$

One-to-one: if  $T(u) = T(v)$



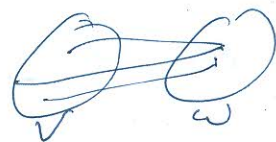
one-to-one

If pre-image of every  $w$  in the range consist of a single vector

Onto: if every element of  $w$  has a preimage in  $V$

Theorem: Let  $T: V \rightarrow W$  be L-T

Then  $T$  is 1-1  $\iff \ker(T) = \{0\}$



Isomorphism: A L-T  $T: V \rightarrow W$  that is 1-1 and onto

is called isomorphism.

Matrix for L-T

$$(1) T(x_1, x_2, x_3) = (2x_1 + x_2 - x_3, x_1 + 3x_2 - 2x_3, 3x_2 + 4x_3)$$

OR

$$(2) T(x) = Ax = \begin{bmatrix} 2 & 1 & -1 \\ -1 & 3 & -2 \\ 0 & 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Q. Finding the standard matrix for the L-T  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined

by  $T(x, y, z) = (x - 2y, 2x + y)$  — (1)

Soln:

vector notation

Matrix notation

$$T(e_1) = T(1, 0, 0)$$

$$= (1 - 2 \times 0, 2 \times 1 + 0)$$

$$= (1, 2)$$

from (1)

$$T(e_1) = T \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$T(e_2) = T(0, 1, 0)$$

$$= (-2, 1)$$

$$T(e_2) = T \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

$$T(e_3) = T(0, 0, 1) = (0, 0)$$

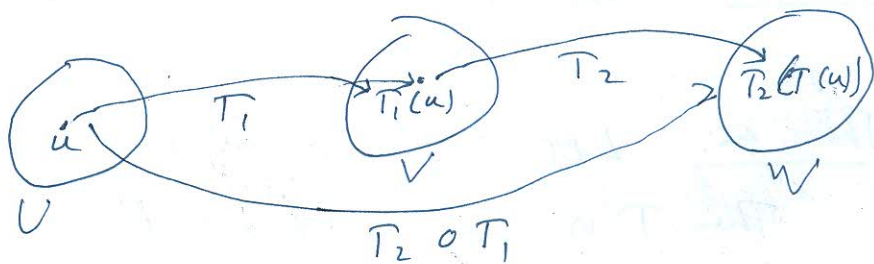
$$T(e_3) = T \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

So

$$A = [T(e_1) \quad T(e_2) \quad T(e_3)]$$

$$= \begin{bmatrix} 1 & -2 & 0 \\ 2 & 1 & 0 \end{bmatrix}$$

Composition





Q. Show that the function  $T(A) = A^T$  is linear Transformation

Soln: we know that to show that  $T$  is linear we have to show

(1)  $T$  Preserve addition:

$$\begin{aligned} T(A+B) &= (A+B)^T \\ &= A^T + B^T \\ &= T(A) + T(B) \end{aligned}$$

(2)  $T$  Preserve scalar multiplication:

$$\begin{aligned} T(KA) &= (KA)^T \\ &= K A^T \\ &= K T(A) \end{aligned}$$

Q2. Show that the map  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  given by  $T(x, y) = (x, 0)$  is linear map

Soln. we know to show  $T$  is linear if it preserve addition & scalar multiplication.

(1)  $T$  Preserve addition: Take any  $v_1 = (x_1, y_1), v_2 = (x_2, y_2) \in \mathbb{R}^2$

$$\begin{aligned} T(v_1 + v_2) &= T((x_1, y_1) + (x_2, y_2)) \\ &= T(x_1 + x_2, y_1 + y_2) \\ &= (x_1 + x_2, 0) \quad \text{by (1)} \\ &= (x_1, 0) + (x_2, 0) \\ &= T(x_1, y_1) + T(x_2, y_2) \quad \text{by (1)} \\ &= T(v_1) + T(v_2) \end{aligned}$$

(2)  $T$  Preserve scalar multiplication:

$$\begin{aligned} T(cv) &= T(c(x, y)) \\ &= T(cx, cy) \\ &= (cx, 0) \quad \text{by (1)} \\ &= c(x, 0) \quad c \text{ is scalar} \\ &= cT(x, y) \quad \text{by (1)} \\ &= cT(v) \end{aligned}$$

Hence  $T$  is a linear map.

Q3 Let  $T(x, y, z) = (3x - 2y + z, 2x - 3y, y - 4z)$   
Write down the standard matrix of  $T$ , and compute  
 $T(2, -1, -1)$ .

Sol:

The matrix will be

$$A = \begin{bmatrix} 3 & -2 & 1 \\ 2 & -3 & 0 \\ 0 & 1 & -4 \end{bmatrix}$$

And

$$T(2, -1, -1) = \begin{bmatrix} 3 & -2 & 1 \\ 2 & -3 & 0 \\ 0 & 1 & -4 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} = \begin{bmatrix} 7 \\ 7 \\ 3 \end{bmatrix}$$

Q Determine whether the function  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , where  $T(x, y) = (x^2, y)$  is linear. (1)

Sol: We know to show  $T$  is linear, we have to show addition & scalar multiplication.

(i)  $T$  preserve addition: Take  $u_1 = (x_1, y_1)$ ,  $u_2 = (x_2, y_2) \in \mathbb{R}^2$

$$\begin{aligned} T(u_1 + u_2) &= T((x_1, y_1) + (x_2, y_2)) \\ &= T(x_1 + x_2, y_1 + y_2) \\ &= ((x_1 + x_2)^2, y_1 + y_2) \quad \text{from (1)} \end{aligned}$$

$$\begin{aligned} &\neq (x_1^2, y_1) + (x_2^2, y_2) \\ &= T(x_1, y_1) + T(x_2, y_2) \\ &= T(u_1) + T(u_2) \end{aligned}$$

So,  $T$  does not preserve additivity, so  
 $T$  is not linear.